Review: Virtual Memory

How is virtual memory realized?

1. **Segmentation**: linear virtual $\rightarrow$ physical address translation with base & bounds registers

2. **Paging**: arbitrary virtual $\rightarrow$ physical address translation by lookup in page table

3. **Segmentation + paging**: first segmentation, then lookup in page table

   $\Rightarrow$ virtual address $\rightarrow$ linear address $\rightarrow$ physical address

   $\Rightarrow$ e.g., used in Intel x86 architecture (32 bits)
Example:¹ x86 Page Table Entry (PTE)

P: present        D: dirty        A: accessed
R/W: read or read+write
U/S: user or supervisor (kernel)
PCD: cache disabled  PWD: cache write through
PAT: extension

¹ Figure from http://duartes.org/gustavo/blog/post/how-the-kernel-manages-your-memory/ (A nice, easy-going tutorial; recommended further reading.)
Why do we need explicit support for sparsely populated virtual address spaces? (= big “empty” gaps in virtual address space)

- Holes of unmapped addresses arise naturally due to shared libraries, kernel memory (at high memory), heap allocations, dynamic thread creation, etc.

- Problem: a flat page table can waste large amounts of memory

- Example: to represent $2^{32}$ bytes = 4Gb of memory with 4Kb pages, we need $2^{32} / 4096 = 1,048,576$ PTEs

  - At 4 bytes (1 = word) per PTE, that’s 1024 pages = 4Mb!
Review: Sparse Address Spaces (2/2)

How are sparsely populated virtual address spaces supported?

▷ Problem with flat page tables: most PTEs are marked invalid to represent “holes”

▷ Idea: represent “holes” implicitly by absence of PTEs, not explicitly with invalid PTEs

▷ Solution: hierarchical page tables: have many shorter page tables, use some bits of virtual address to look up which page table to use in a page table directory.
Example: \(^2\) x86 Multi-level Page Table

Figure from Bovet and Cesati, Understanding the Linux Kernel, O Reilly Media, 3rd edition, 2005.
Review: Missing Page Table Entries

What happens when a virtual address cannot be resolved by the MMU?

» “cannot be resolved” = either entry in page table directory is marked invalid, or PTE in page table is marked invalid (= not present)

» The result is a page fault: an exception is triggered and control is transferred to the OS-provided page fault handler.

» Page fault handler has access to all register contents, faulting instruction, and can implement arbitrary policy.
How do page faults differ from system calls?

And from other exceptions or interrupts?

» In large parts system calls, exceptions/traps, and interrupts are the same.

» Control flow diverted to OS-provided handler; processor switches to kernel mode; register contents and status code provided.

» Key difference: after system call or interrupt, resume execution at next instruction, but after page fault, re-execute faulting instruction.
Exception during exception handling

What happens if a page fault (or any other exception/trap) is encountered while handling a page fault (or any other exception/trap)?

» On x86, a **double fault exception** (0x8) is generated, for which the OS must provide an exception handler.

» What happens if an exception is encountered while handling a **double** fault?

» On x86, a **triple fault exception** is generated, which **immediately resets** the system.
Shared Memory

What does it mean for a page to be “shared”?

➢ Multiple processes can read from and/or write to the same physical page.

➢ Historic platforms: all physical memory shared
  ➢ any thread can read / write any memory location

➢ With segmentation / paging: no virtual memory shared at all: → all processes perfectly isolated

➢ But selective sharing is useful. How to re-enable it?
How to give access to a page of memory?

What does the OS have to do to share a page $P$ of memory?

» Simply **insert a page table entry** (PTE) for the shared physical page in the page table of each process that shares $P$

» Any number of PTEs in any number of page tables can refer to the same physical page

» **Same physical page** can be mapped by different processes at **different virtual addresses**

» beware of pointers in shared memory segments!
How to take away access to a page of memory?

What does the OS have to do to “un-share” a page of memory?

» Remove PTE (= mark as non-present) in the page table of process that loses access rights.

» Is this enough?

» No! Stale mapping could still exist in translation look-aside buffers (TLBs) of one or more cores
Review: When to flush the TLB?

» When introducing a **new mapping** — adding a PTE to the page table at a previously invalid virtual address — **no TLB flush** is required.

» When changing an **existing mapping** — overwriting a valid PTE — a **TLB flush** is required: a *stale TLB* entry may exist.

» When **removing a mapping** — zeroing a valid PTE — a **TLB flush** is required.

» What happens on multiprocessors?
When and why does the OS share memory?

1. **Explicitly**, when requested by applications
   - To enable efficient *communication*

2. **Implicitly**, to optimize resource usage
   - Memory is scarce and valuable, must be used efficiently
   - This happens *transparently* to applications
Explicitly Shared Memory (1/2)

Example: In POSIX, user process can request a shared memory segment with `mmap()`.

```c
void *mmap(void *addr, size_t length, int prot,
           int flags, int fd, off_t offset);
```

- `addr` — where to map the memory in virtual address space
- `length` — how much to map (multiple of page size)
- `prot` — combination of PROT_EXEC, PROT_READ, PROT_WRITE, or PROT_NONE
- `flags` — MAP_SHARED and many special cases...
- `fd` — file to map
- `offset` — offset within file where the mapping starts
Explicitly Shared Memory (2/2)

- **Access control**: two processes may (explicitly) share memory if and only if they can map the same file (*file system permissions* apply)

- can create temporary files as needed

- **Backing pages**: file is represented in memory by (physical) pages anyway.

- **Application-controlled**: OS just installs / removes PTEs corresponding to requested operations.
Implicitly Shared Memory

Basic idea: store redundant information only once

Examples:

» Multiple instances of the same program, but only one read-only copy of text segment (code)

» ...only one read-only copy of constant data

» Shared library used by many processes, but only one read-only copy of library code and constants
Can we share even more?

Memory is scarce and copying is expensive. Can we share additional memory? Heap memory? Stack memory? Global variables?

» Problem: Heap, stack, globals are writable pages.

» Naïve sharing of writable memory
   → processes overwrite each other’s updates!

» But: most writable memory is never written to in a typical process.

» Which memory is written to depends on input.
Copy-on-Write (CoW)

**Idea**: Need a new copy of a *writeable* page only each time it is actually written to.

- We can allocate such copies *lazily* on demand.
- When a write occurs, *transparently* make a copy of the *shared* page and give the new copy to the writing process, making it *private*.
- To do so, we must *trap* (= detect) a write attempt.
  - This can be accomplished with PTE protection bits…
- **Tradeoff**: Nothing gained if *all* pages are written to, but most programs modify only *some* of their memory.
How does CoW work?

1. Shared page is marked as *read-only* in page tables of all processes that share it.
   
   » OS must keep track of in which address spaces a physical page is mapped

2. As a result, any write attempt leads to a page fault.

3. When a process traps into the kernel due to a write attempt, a new physical page is allocated and a copy of the shared page is made.

4. The page table of the process that trapped is updated to point to the newly allocated page, which is mapped with *read-write* permissions.

5. The process that trapped is resumed by re-executing the faulting instruction.
Applications of CoW

Some examples where CoW can have great effect:

» In UNIX and UNIX-like systems, new processes are created with `fork()` by *duplicating* the calling process. The semantics of `fork()` require the entire address space to be “copied” — this is much faster with CoW.

» Shared libraries with rarely-changed defaults

» *Privately* mapped files: where changes by one process should not be seen by other processes.
Where does paged memory come from?

With CoW and demand paging, the page fault handler lazily sets up the page based on an authoritative reference page (e.g., file contents).

Generalizing this notion, does the authoritative source always have to be local?

» No! The page fault handler can determine contents of page arbitrarily. E.g., via a network.
Distributed Shared Memory

What if we want to write multithreaded program that takes advantage of all cores in a cluster connected by a fast network?

» We can create a single virtual address space that spans separate physical memories.

» The same virtual address space is used by threads on all hosts.

» Basic idea: map pages as always, but the underlying physical reference page may reside on a remote host.

» To make this work, transfer page contents as needed: from remote host’s memory when paging in; to remote host’s memory when paging out (or when flushing dirty pages).
Coordinating Writes in a DSM

How can a node safely write to a page that may be mapped on remote hosts?

» We can keep a cache of read-only copies of a page on multiple hosts simultaneously.

» When a write traps on any host, invalidate the page on all other hosts by (a) evicting it from their caches and (b) unmapping it from the virtual address spaces of their local processes.

» Once a host is the exclusive owner of page, it can allow the local process to write to it.
DSM relies on read-only and read-mostly pages

Remember: many pages are never, or only rarely, written to. Further, threads rarely access all pages. This is essential to making DSM work. Why?

» If all shared pages are written to, the speed of the computation will be limited by the network speed (to propagate updates).

» If each thread accesses most pages, these will not all fit into its local memory; the speed of the computation will be limited by the network speed as it pages in data from remote hosts.
DSM Principles in Modern Systems

DSM at the process level has fallen out of favor in current system design. But the basic principles are widely used nonetheless. Where and why?

» A modern multicore processor resembles a “distributed systems on a chip”.

» Multiple sockets, with multiple cores and shared caches each.

» Very fast local caches, much slower access to remote caches or global memory.

» **Cache consistency protocols**, operating at the level of cache lines, are conceptually very similar to page-based DSMs.
Common VM “Trick”: Guard Pages

How to catch heap or global buffer over- and underflows?

» Programs tend to write beyond allocated buffers...
  » e.g., off-by-one errors, wrongly computed bounds

» These can be difficult to catch during testing, but can have disastrous consequences (security vulnerabilities).

» Guard pages: between any two heap allocations, keep some unmapped virtual addresses
  » access past buffer = page fault = obviously an error
What to do with segments?

If we have both paging and segmentation, are segments still useful?

» Depends. Segments are not necessary to provide virtual memory.
   » E.g., Linux does not use segments to realize address spaces even if the hardware supports segmentation.

» However, there are other techniques for which segments can be useful.
   » Two examples here...
Another Defensive Technique: Stack Canaries

How to catch buffer overflows on the stack?

» **Security vulnerability**: buffer overflows on the stack can overwrite return address, hijack control flow.

» **Defense**: place *canary value* on stack before return address — before returning from function, check for overwritten canary value.

» But where to store reference value such that attacker can’t get to it?

» One solution: in a *separate segment*, the position of which is randomized when the program is loaded.
How to Implement Thread-local Variables?

Thread-local variable: each thread has a private copy of a variable, can be accessed without locks.

Per-CPU variable: in kernel, each core has a private copy of a variable. (Ex: scheduler queues)

» Same code for all cores / threads, but must reference different physical addresses. How?
» One approach: use segment for thread-local variables.
» Each core / thread uses different base & bounds registers